

Volumetric Rendering

3D Computer Graphics

Barnabás “Barney” Börzsök
bborcsok@iit.bme.hu

Computer Graphics Group (IIT)
Faculty of Electrical Engineering and Informatics
Budapest University of Technology and Economics

Spring Semester, 2022/2023

Motivation



Motivation



Motivation



Te Ka, a character from Disney's Moana (2016). Illustration from [1].

Motivation

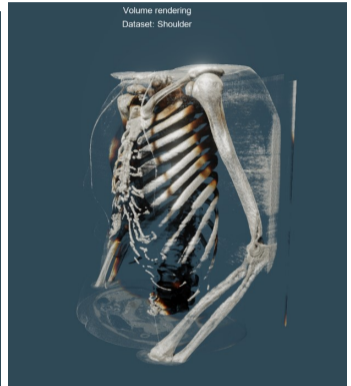
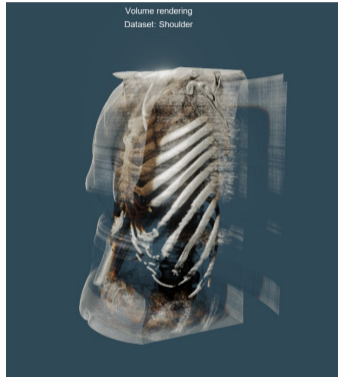
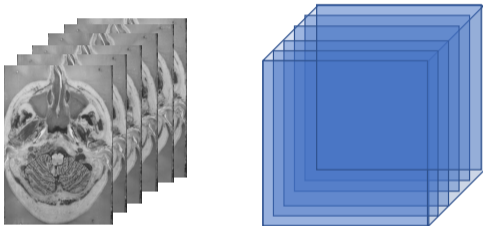
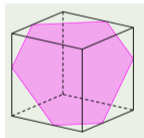
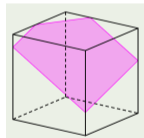
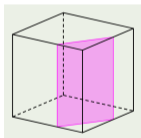
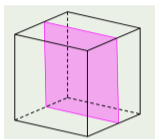
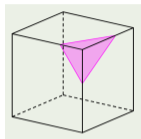
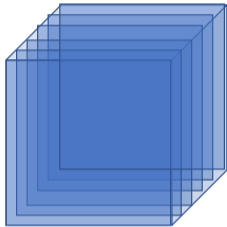
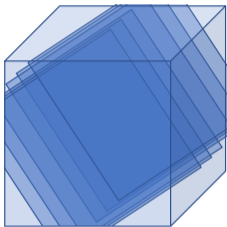


Illustration from [2].

Volume Rendering with Slices



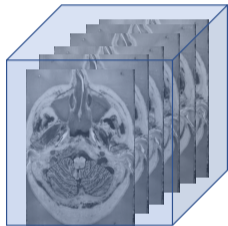
Volume Rendering with Slices



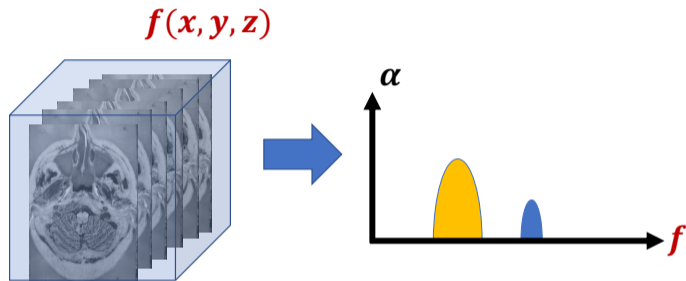
Interactive box-plane intersections: <https://www.geogebra.org/m/aY75dEkf>

Transfer Function

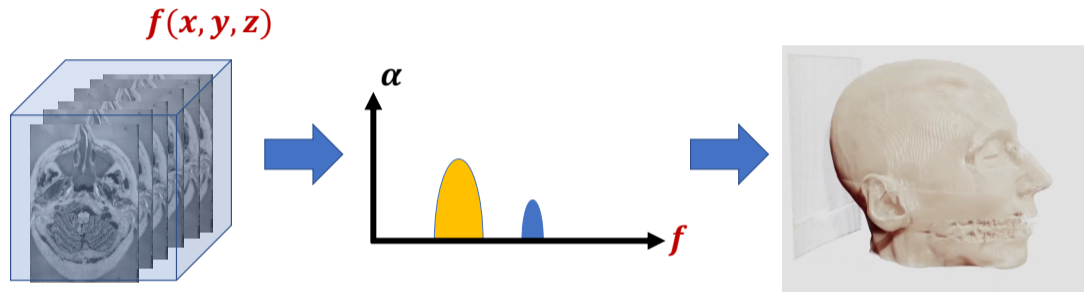
$$f(x, y, z)$$



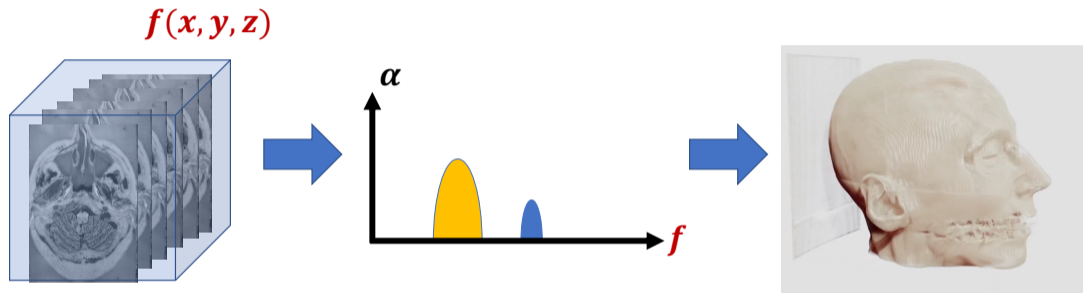
Transfer Function



Transfer Function

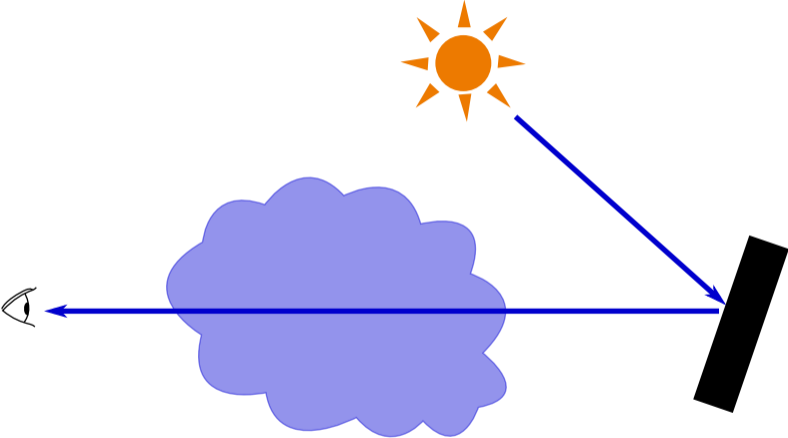


Transfer Function

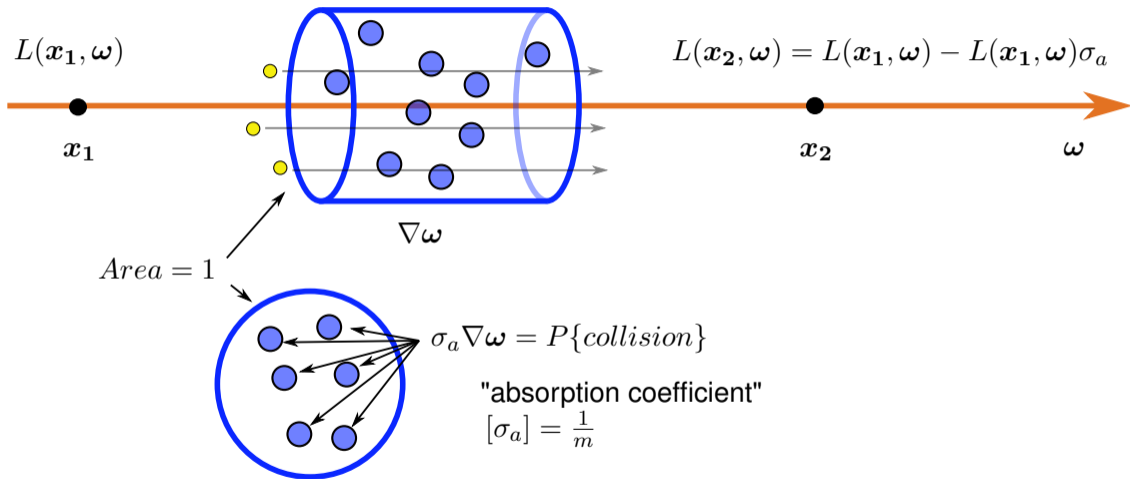


Let's see this in action! (Video Demo)

Propagation of light in a medium

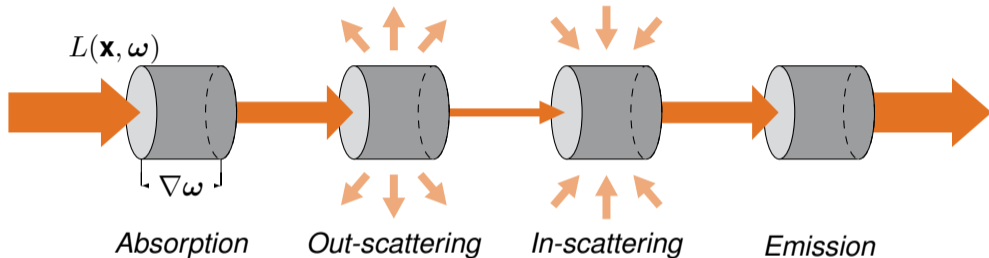


Change of radiance in a differential volume

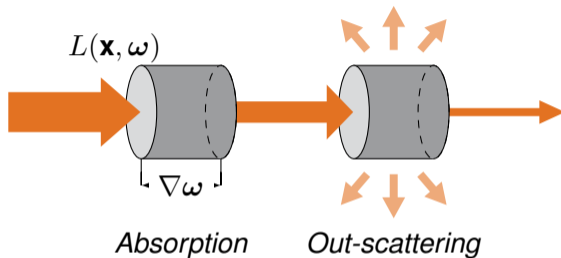


Possible interactions

between the volume and the light traveling through the medium



Summing up the losses



σ_a : Absorption coefficient

σ_s : Scattering coefficient

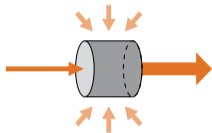
$\sigma_a + \sigma_s = \sigma_t$: Extinction coefficient

$\sigma_t \implies$ Homogeneous

We lose $\sigma_t(\mathbf{x})L(\mathbf{x}, \omega)$ radiance due to *absorption* and *out-scattering*.

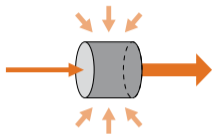
$\sigma_t(\mathbf{x}) \implies$ Heterogeneous

In-scattered radiance



$$L_s(\mathbf{x}, \boldsymbol{\omega}) = \int_{S^2} f_p(\mathbf{x}, \boldsymbol{\omega}, \boldsymbol{\omega}') L_i(\mathbf{x}, \boldsymbol{\omega}') d\boldsymbol{\omega}'$$

In-scattered radiance



$$L_s(\mathbf{x}, \boldsymbol{\omega}) = \int_{S^2} f_p(\mathbf{x}, \boldsymbol{\omega}, \boldsymbol{\omega}') L_i(\mathbf{x}, \boldsymbol{\omega}') d\boldsymbol{\omega}'$$

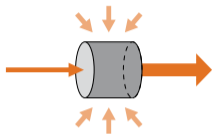
Phase function

$$f_p(\mathbf{x}, \boldsymbol{\omega}, \boldsymbol{\omega}')$$

$\approx BSDF$

(in surface rendering)

In-scattered radiance



$$L_s(\mathbf{x}, \omega) = \int_{S^2} f_p(\mathbf{x}, \omega, \omega') L_i(\mathbf{x}, \omega') d\omega'$$

Phase function

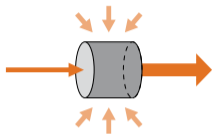
$$f_p(\mathbf{x}, \omega, \omega')$$

\approx BSDF

(in surface rendering)

- scattering at point \mathbf{x} , given incident (ω) and outgoing (ω') directions

In-scattered radiance



$$L_s(\mathbf{x}, \omega) = \int_{S^2} f_p(\mathbf{x}, \omega, \omega') L_i(\mathbf{x}, \omega') d\omega'$$

Phase function

$$f_p(\mathbf{x}, \omega, \omega')$$

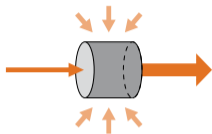
$\approx BSDF$

(in surface rendering)

■ scattering at point \mathbf{x} , given incident (ω) and outgoing (ω') directions

■ $\int_{S^2} f_p = 1$

In-scattered radiance



$$L_s(\mathbf{x}, \omega) = \int_{S^2} f_p(\mathbf{x}, \omega, \omega') L_i(\mathbf{x}, \omega') d\omega'$$

Phase function

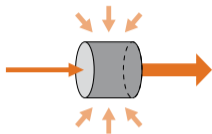
$$f_p(\mathbf{x}, \omega, \omega')$$

$\approx BSDF$

(in surface rendering)

- scattering at point \mathbf{x} , given incident (ω) and outgoing (ω') directions
- $\int_{S^2} f_p = 1$
- $f_p(\theta) |_{\theta=\angle(\omega, \omega')}$

In-scattered radiance



$$L_s(\mathbf{x}, \boldsymbol{\omega}) = \int_{S^2} f_p(\mathbf{x}, \boldsymbol{\omega}, \boldsymbol{\omega}') L_i(\mathbf{x}, \boldsymbol{\omega}') d\boldsymbol{\omega}'$$

Phase function

$$f_p(\mathbf{x}, \boldsymbol{\omega}, \boldsymbol{\omega}')$$

$\approx BSDF$

(in surface rendering)

■ scattering at point \mathbf{x} , given incident ($\boldsymbol{\omega}$) and outgoing ($\boldsymbol{\omega}'$) directions

■ $\int_{S^2} f_p = 1$

■ $f_p(\theta) \big|_{\theta=\angle(\boldsymbol{\omega}, \boldsymbol{\omega}')}$

■ $f_p(\mathbf{x}, \boldsymbol{\omega}, \boldsymbol{\omega}') = 1/(4\pi)$, if the medium is *isotropic*

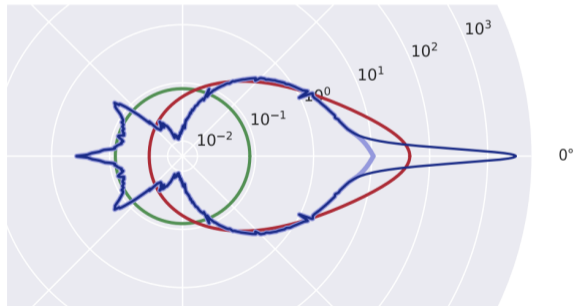
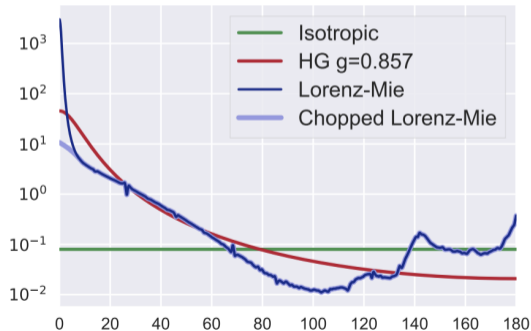
(otherwise, *anisotropic*)

Phase function examples

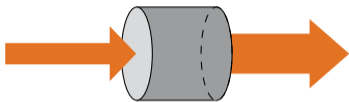
■ isotropic: $f_p = \frac{1}{4\pi}$

■ Henyey-Greenstein: $f_p(\theta) = \frac{1}{4\pi} \frac{1-g^2}{(1+g^2-2g \cos(\theta))^{3/2}}$

Illustration from [5]:



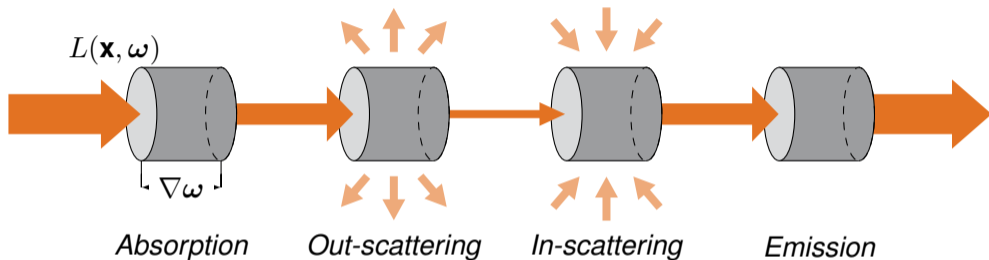
Emission



$$L_e(\mathbf{x}, \boldsymbol{\omega})$$

$$\sigma_a(\mathbf{x})L_e(\mathbf{x}, \boldsymbol{\omega})$$

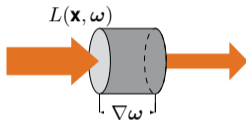
Assembling all the parts



- Loses $\sigma_a L(x, \omega)$ due to absorption
- Loses $\sigma_s L(x, \omega)$ due to out-scattering
- Gains $\sigma_s L_i(x, \omega)$ due to in-scattering
- Gains $\sigma_a L_e(x, \omega)$ due to emission

RTE – Radiative Transfer Equation

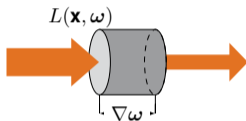
The change in radiance L traveling along direction ω through a differential volume element at point \mathbf{x} .



$$(\omega \nabla)L(\mathbf{x}, \omega) = \underbrace{-\sigma_t(\mathbf{x})L(\mathbf{x}, \omega)}_{\text{Extinction}} + \underbrace{\sigma_s(\mathbf{x})L_s(\mathbf{x}, \omega)}_{\text{In-scattering}} + \underbrace{\sigma_a(\mathbf{x})L_e(\mathbf{x}, \omega)}_{\text{Emission}}$$

RTE – Radiative Transfer Equation

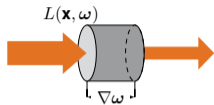
The change in radiance L traveling along direction ω through a differential volume element at point \mathbf{x} .



$$(\omega \nabla)L(\mathbf{x}, \omega) = \underbrace{-\sigma_t(\mathbf{x})L(\mathbf{x}, \omega)}_{\text{Extinction}} + \underbrace{\sigma_s(\mathbf{x})L_s(\mathbf{x}, \omega)}_{\text{In-scattering}} + \underbrace{\sigma_a(\mathbf{x})L_e(\mathbf{x}, \omega)}_{\text{Emission}}$$

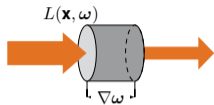
Let's integrate it!

Integrating the loss of radiance



$$L(\mathbf{x} + dx) = L(\mathbf{x}) - L(\mathbf{x})\sigma_t(\mathbf{x})dx \Big|_{dx=\nabla\omega, L(\mathbf{x})=L(\mathbf{x},\omega)}$$

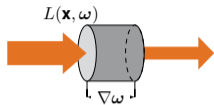
Integrating the loss of radiance



$$L(\mathbf{x} + dx) = L(\mathbf{x}) - L(\mathbf{x})\sigma_t(\mathbf{x})dx \Big|_{dx=\nabla\omega, L(\mathbf{x})=L(\mathbf{x},\omega)}$$

$$\boxed{\frac{dL(\mathbf{x})}{dx} = -L(\mathbf{x})\sigma_t(\mathbf{x})} \text{ ("exponential extinction")}$$

Integrating the loss of radiance

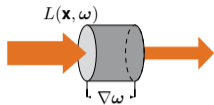


$$L(\mathbf{x} + dx) = L(\mathbf{x}) - L(\mathbf{x})\sigma_t(\mathbf{x})dx \Big|_{dx=\nabla\omega, L(\mathbf{x})=L(\mathbf{x},\omega)}$$

$$\boxed{\frac{dL(\mathbf{x})}{dx} = -L(\mathbf{x})\sigma_t(\mathbf{x})} \text{ ("exponential extinction")}$$

$$\int_{L(x)}^{L(x+S)} \frac{1}{L} dL = - \int_0^S \sigma_t(\mathbf{x}) dx$$

Integrating the loss of radiance



$$L(\mathbf{x} + dx) = L(\mathbf{x}) - L(\mathbf{x})\sigma_t(\mathbf{x})dx \Big|_{dx=\nabla\omega, L(\mathbf{x})=L(\mathbf{x},\omega)}$$

$$\boxed{\frac{dL(\mathbf{x})}{dx} = -L(\mathbf{x})\sigma_t(\mathbf{x})} \text{ ("exponential extinction")}$$

$$\int_{L(\mathbf{x})}^{L(\mathbf{x}+S)} \frac{1}{L} dL = - \int_0^S \sigma_t(\mathbf{x}) dx$$

$$\ln(L(\mathbf{x} + S)) - \ln(L(\mathbf{x})) = - \int_0^S \sigma_t(\mathbf{x}) dx$$

Transmittance

The Beer-Lambert Law

$$\frac{dL(\mathbf{x})}{dx} = -L(\mathbf{x})\sigma_t(\mathbf{x}) \quad (\text{"exponential extinction"})$$

$$L(\mathbf{x} + S) = L(\mathbf{x})e^{-\int_0^S \sigma_t(\mathbf{x}+s)ds}$$

Transmittance

The Beer-Lambert Law

$$\frac{dL(\mathbf{x})}{dx} = -L(\mathbf{x})\sigma_t(\mathbf{x}) \quad (\text{"exponential extinction"})$$

$$L(\mathbf{x} + S) = L(\mathbf{x})e^{-\int_0^S \sigma_t(\mathbf{x}+s)ds}$$

Usually written as:

$$e^{-\int_0^y \sigma_t(\mathbf{x}-s\omega)ds} = T(\mathbf{x}, \mathbf{y})$$

"transmittance coefficient" $T(\mathbf{x}, \mathbf{y})$

net reduction factor between \mathbf{x} and \mathbf{y}
due to absorption and out-scattering

Transmittance

The Beer-Lambert Law

$$\frac{dL(\mathbf{x})}{dx} = -L(\mathbf{x})\sigma_t(\mathbf{x}) \quad (\text{"exponential extinction"})$$

$$L(\mathbf{x} + S) = L(\mathbf{x})e^{-\int_0^S \sigma_t(\mathbf{x}+s)ds}$$

Usually written as:

$$e^{-\int_0^y \sigma_t(\mathbf{x}-s\boldsymbol{\omega})ds} = T(\mathbf{x}, \mathbf{y})$$

"transmittance coefficient" $T(\mathbf{x}, \mathbf{y})$

net reduction factor between \mathbf{x} and \mathbf{y}
due to absorption and out-scattering

$$\int_0^y \sigma_t(\mathbf{x} - s\boldsymbol{\omega})ds = \tau(\mathbf{x}, \mathbf{y})$$

"optical thickness" τ

Transmittance

The Beer-Lambert Law

$$\frac{dL(\mathbf{x})}{dx} = -L(\mathbf{x})\sigma_t(\mathbf{x}) \quad (\text{"exponential extinction"})$$

$$L(\mathbf{x} + S) = L(\mathbf{x})e^{-\int_0^S \sigma_t(\mathbf{x}+s)ds}$$

Usually written as:

$$e^{-\int_0^y \sigma_t(\mathbf{x}-s\omega)ds} = T(\mathbf{x}, \mathbf{y})$$

"transmittance coefficient" $T(\mathbf{x}, \mathbf{y})$

net reduction factor between \mathbf{x} and \mathbf{y}
due to absorption and out-scattering

$$\int_0^y \sigma_t(\mathbf{x} - s\omega)ds = \tau(\mathbf{x}, \mathbf{y})$$

"optical thickness" τ

$$T(t) = e^{-\tau(t)} = e^{-\int_0^t \sigma_t(\mathbf{x}-s\omega)ds}$$

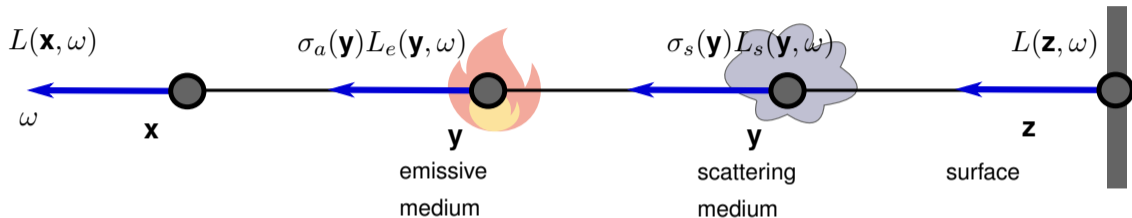
over distance t

RTE – Radiative Transfer Equation

The integral version

$$L(\mathbf{x}, \boldsymbol{\omega}) = \int_0^\infty \underbrace{e^{-\int_0^y \sigma_t(\mathbf{x}-s\boldsymbol{\omega})ds}}_{\text{Transmittance } T(\mathbf{x},\mathbf{y})} \left[\underbrace{\sigma_s(\mathbf{y})L_s(\mathbf{y}, \boldsymbol{\omega})}_{\text{in-scatter}} + \underbrace{\sigma_a(\mathbf{y})L_e(\mathbf{y}, \boldsymbol{\omega})}_{\text{emission}} \right] d\mathbf{y}$$

VRE – Volume Rendering Equation



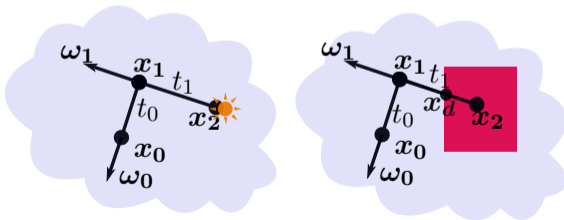
$$L(\mathbf{x}, \omega) = \int_0^z T(\mathbf{x}, \mathbf{y}) [\sigma_a(\mathbf{y})L_e(\mathbf{y}, \omega) + \sigma_s(\mathbf{y})L_s(\mathbf{y}, \omega)] dy + T(\mathbf{x}, \mathbf{z})L(\mathbf{z}, \omega)$$

Tracking

In homogeneous volumes

- Simulate how a photon bounces around inside a volume
- Explicitly modeling absorption and scattering effects

$$T(t) = e^{-\int_0^t \sigma_t(x-s\omega) ds} = e^{-\int_0^t \sigma_t ds} = \boxed{e^{-\sigma_t t} = T(t)}$$

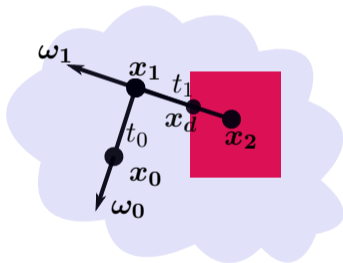


Tracking

In heterogeneous volumes

What happens if the volume is **not homogeneous**? $\implies \sigma_t(\mathbf{x})$

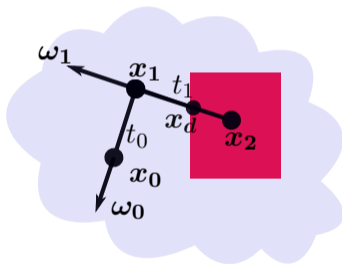
\implies apply closed-form tracking to homogeneous sub-parts? $\implies \sigma_t$



Tracking

In heterogeneous volumes

What happens if the volume is **not homogeneous**? $\implies \sigma_t(\mathbf{x})$
 \implies apply closed-form tracking to homogeneous sub-parts? $\implies \sigma_t$

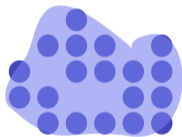


If only...

Delta tracking / Woodcock tracking

Introducing null-collisions

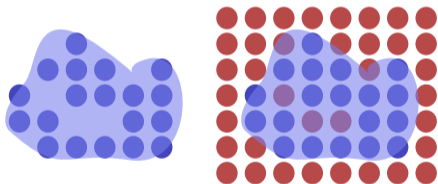
1. Problem: the volume is heterogeneous
2. Idea: **Increase the number of interactions** to make it homogeneous, but **reject** some of the interactions \implies **null-collisions**



Delta tracking / Woodcock tracking

Introducing null-collisions

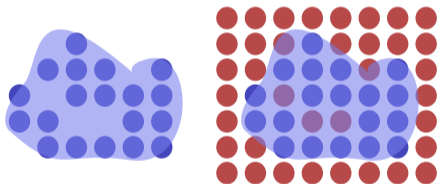
1. Problem: the volume is heterogeneous
2. Idea: **Increase the number of interactions** to make it homogeneous, but **reject** some of the interactions \implies **null-collisions**



Delta tracking / Woodcock tracking

Introducing null-collisions

1. Problem: the volume is heterogeneous
2. Idea: **Increase the number of interactions** to make it homogeneous, but **reject** some of the interactions \implies **null-collisions**



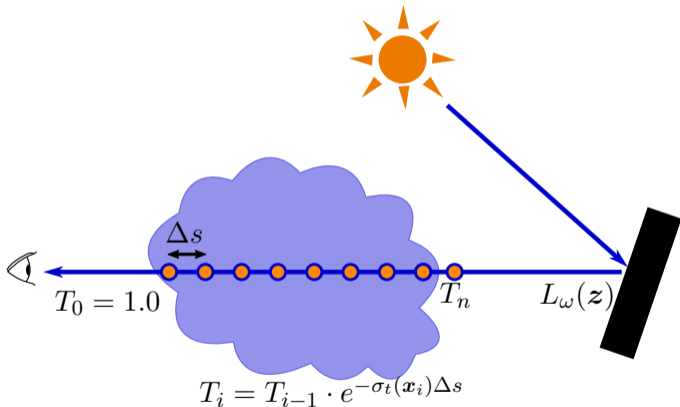
$$\bar{\sigma} = \sigma_s(\mathbf{x}) + \sigma_a(\mathbf{x}) + \sigma_n(\mathbf{x})$$

$$\sigma_n(\mathbf{x}) = \bar{\sigma} - \sigma_t(\mathbf{x})$$

$$T_{\bar{\sigma}}(\mathbf{x}, \mathbf{y}) = e^{-\int_0^y \sigma_s(s) + \sigma_a(s) + \sigma_n(s) ds}$$

Transmittance Estimation

Ray Marching ¹



¹You will use ray marching during tomorrow's lab session for finding surfaces.

Acceleration Data Structures

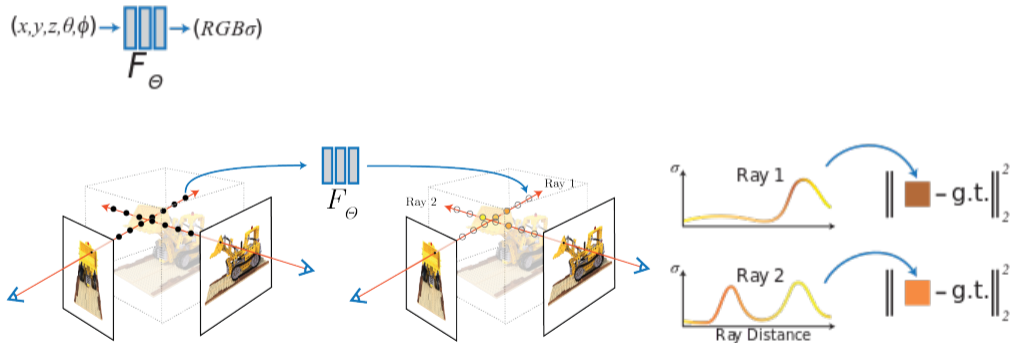
- Spatially-varying properties
- Data access usually dominates the render time
 - ⇒ data structures are key for achieving good performance
- Volume data can quickly grow into hundreds of gigabytes for production
 - For example, peak storage needed for a single shot of the movie Soul was 80 TBs.[3]

<https://www.openvdb.org/>

<https://developer.nvidia.com/nanovdb>

Bonus: NeRF: Neural Radiance Fields

- See [4] (<https://www.matthwttancik.com/nerf>)



Bonus: Deep Learning for Rendering Clouds

- Vast cost of data access and tracking particles in high-albedo volumes (resulting in lots of scattering) – e.g. clouds
- Approximating the indirect in-scattered radiance with a Neural Network.
- They achieved $24\times$ speed-up! See [5].



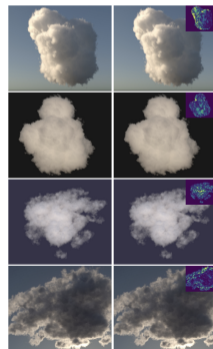
(a) 1 interaction
Render time = 0.017 h

(a) 4 interactions
Render time = 0.89 h

(a) 16 interactions
Render time = 6.5 h

(a) 64 interactions
Render time = 16 h

(a) All interactions
Render time = 34 h



(e) PT reference

(f) RPNN (ours)

Volumetric Rendering

3D Computer Graphics

Barnabás “Barney” Börzsök
bborcsok@iit.bme.hu

Computer Graphics Group (IIT)
Faculty of Electrical Engineering and Informatics
Budapest University of Technology and Economics

Spring Semester, 2022/2023

Further Reading I

- [1] Julian Fong, Magnus Wrenninge, Christopher Kulla, and Ralf Habel. Production Volume Rendering: SIGGRAPH 2017 Course. 2017.
<https://doi.org/10.1145/3084873.3084907>.
- [2] Zoltán Simon. Térfigatvizualizációs algoritmusok implementálása grafikus hardveren. Bsc thesis, 2022. <https://diplomaterv.vik.bme.hu/hu/Theses/Terfigatvizualizacios-algoritmusok>
<https://github.com/TheFlyingPiano99/HomebrewGraphicsEngine>.
- [3] Sasha Ouellet, Daniel Garcia, Stephen Gustafson, Matt Kuruc, Michael Lorenzen, George Nguyen, and Grace Gilbert. Rasterizing volumes and surfaces for crowds on soul. In *ACM SIGGRAPH 2020 Talks*, 2020.
<https://doi.org/10.1145/3388767.3407374>.
- [4] Ben Mildenhall, Pratul P. Srinivasan, Matthew Tancik, Jonathan T. Barron, Ravi Ramamoorthi, and Ren Ng. Nerf: Representing scenes as neural radiance fields for

Further Reading II

view synthesis. In *ECCV*, 2020. <https://www.matthewtancik.com/nerf>.

- [5] Simon Kallweit, Thomas Müller, Brian McWilliams, Markus Gross, and Jan Novák. Deep scattering: Rendering atmospheric clouds with radiance-predicting neural networks. *ACM Trans. Graph.*, 2017. URL <https://doi.org/10.1145/3130800.3130880>.
<https://studios.disneyresearch.com/2017/11/20/deep-scattering-rendering-atmospheric-clouds-with-radiance-predict>.